



GEOMETRY OF REACTIVE POWER: A DIVERTIMENTO

August 2009

A. M. Stanković

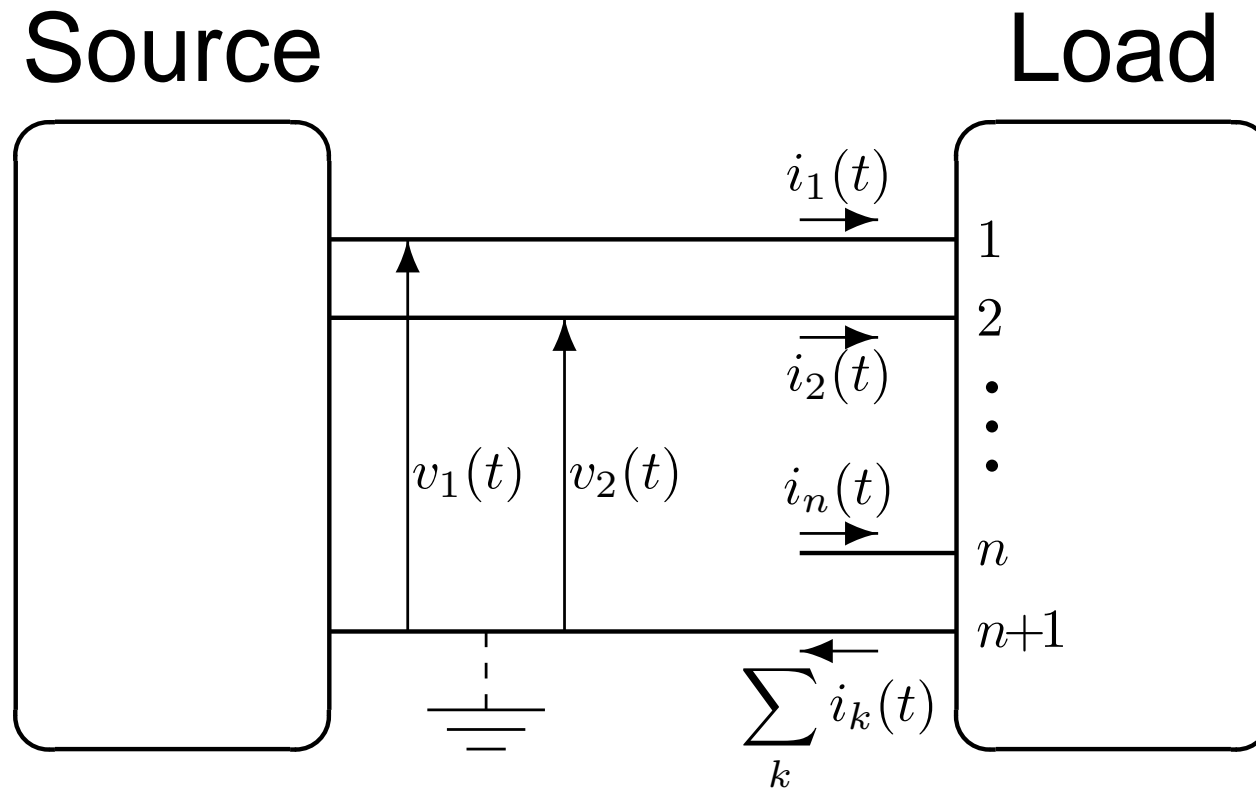
H. Lev-Ari

Northeastern University, Boston

astankov@ece.neu.edu

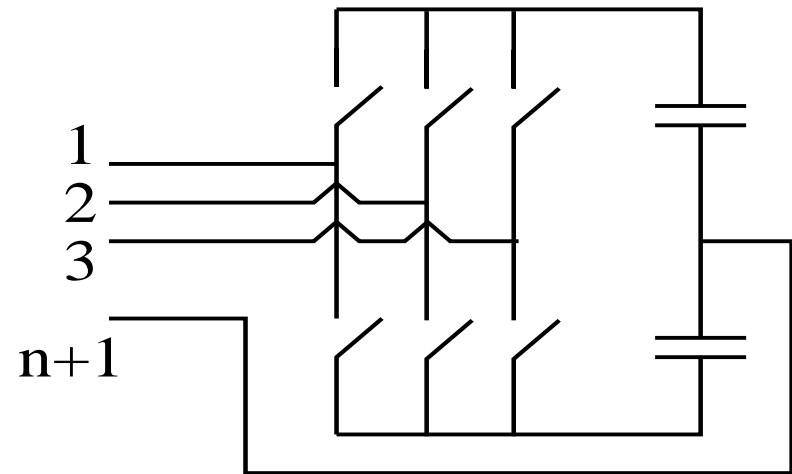
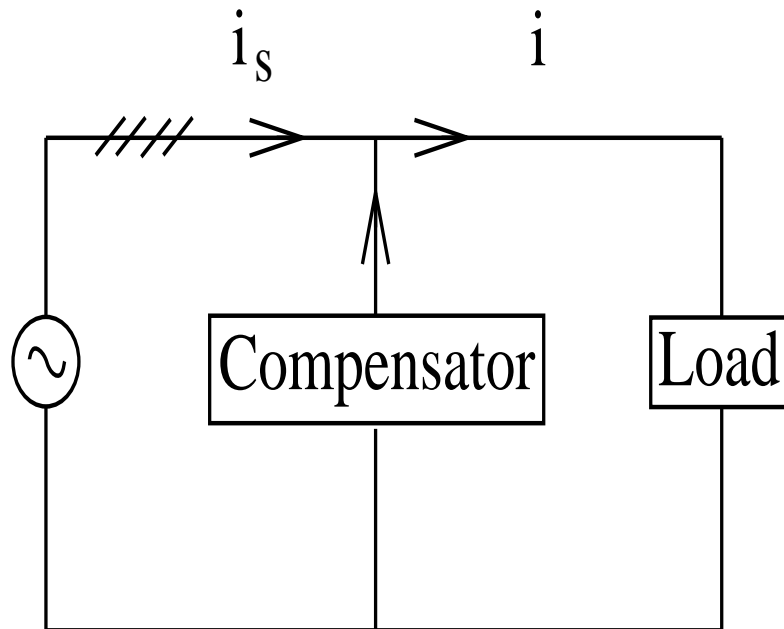
Problem Formulation

Consider a possibly unbalanced system with n phases, $n + 1$ conductors (with possibly different resistances), and arbitrary many harmonics:



Problem Formulation (2)

Compensation framework



Compensator

For now, all time domain (row-)vector waveforms $x(t)$ are periodic, with period T ; let $\omega = 2\pi/T$ so the Fourier coefficients [Steinmetz] are

$$X_\ell = \frac{1}{T} \int_T x(t) e^{-j\ell\omega t} dt \stackrel{\text{def}}{=} \langle x(t) \rangle_\ell \quad (1)$$

Agreement on Reactive Power

Standard definitions [Buchholz, Schallenberger, Stanley]:

$$\|V\|^2 = \langle v v^\top \rangle_0, \quad \|I\|^2 = \langle i i^\top \rangle_0, \quad S = \|V\| \|I\|$$

$$P = \langle i^\top v \rangle_0, \quad Q^2 = S^2 - P^2, \quad k_{PF} = \frac{P}{S}$$

Agreement on Reactive Power

Standard definitions [Buchholz, Schallenberger, Stanley]:

$$\|V\|^2 = \langle v v^\top \rangle_0, \quad \|I\|^2 = \langle i i^\top \rangle_0, \quad S = \|V\| \|I\|$$

$$P = \langle i^\top v \rangle_0, \quad Q^2 = S^2 - P^2, \quad k_{PF} = \frac{P}{S}$$

For single frequency and single phase/ balanced polyphase in steady state:

$$P = \|V\| \|I\| \cos \phi_1, \quad Q = \|V\| \|I\| \sin \phi_1 = Q_{B1}$$

$$k_{PF} = \cos \phi_1, \quad S_c \triangleq P + jQ$$

Agreement on Reactive Power

Standard definitions [Buchholz, Schallenberger, Stanley]:

$$\|V\|^2 = \langle v v^\top \rangle_0, \quad \|I\|^2 = \langle i i^\top \rangle_0, \quad S = \|V\| \|I\|$$

$$P = \langle i^\top v \rangle_0, \quad Q^2 = S^2 - P^2, \quad k_{PF} = \frac{P}{S}$$

For single frequency and single phase/ balanced polyphase in steady state:

$$P = \|V\| \|I\| \cos \phi_1, \quad Q = \|V\| \|I\| \sin \phi_1 = Q_{B1}$$

$$k_{PF} = \cos \phi_1, \quad S_c \triangleq P + jQ$$

In multi-frequency $k_{PF} \neq \cos \phi_1$, [Steinmetz 1898]; similarly for unbalanced.

Presentation Map

- Multivectors and Geometric Algebra,
- Polyphase Sinusoidal,
- Non-sinusoidal,
- Transients.

Geometric (Clifford) Algebra

$v(t)$ and $i(t)$ are row vectors, elements in the Hilbert space [Quade 1939] of all n -phase, square-integrable, T -periodic waveforms, with the inner product

$$\langle x, y \rangle \triangleq \frac{1}{T} \int_T x(s) y^T(s) ds \quad (2)$$

The geometric algebra we consider is generated by a **voltage-derived** finite-dimensional subspace of the Hilbert space. A vector \mathbf{x} in the given Euclidean space satisfies

$$\mathbf{x}^2 = \langle \mathbf{x}, \mathbf{x} \rangle \equiv \|\mathbf{x}\|^2$$

For two distinct vectors

$$\mathbf{x}\mathbf{y} - \langle \mathbf{x}, \mathbf{y} \rangle \triangleq \mathbf{x} \wedge \mathbf{y}$$

where $\mathbf{y} \wedge \mathbf{x} = -\mathbf{x} \wedge \mathbf{y}$.

Geometric Algebra (2)

Consider a single phase sinusoidal circuit and let $\mathbf{e}_1 = \sqrt{2} \cos \omega t$, $\mathbf{e}_2 = \sqrt{2} \sin \omega t$. Then

$$\begin{aligned}v(t) &\equiv \mathbf{v} = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 \\i(t) &\equiv \mathbf{i} = \beta_1 \mathbf{e}_1 + \beta_2 \mathbf{e}_2\end{aligned}$$

The apparent power multivector is then

$$\mathcal{S} \triangleq \mathbf{v} \mathbf{i} = \underbrace{\alpha_1 \beta_1 + \alpha_2 \beta_2}_{\langle \mathbf{v}, \mathbf{i} \rangle} + \underbrace{(\alpha_1 \beta_2 - \alpha_2 \beta_1) \mathbf{e}_1 \mathbf{e}_2}_{\mathbf{v} \wedge \mathbf{i}}$$

where we used the rules $\mathbf{e}_i^2 = 1$, $\mathbf{e}_2 \mathbf{e}_1 = -\mathbf{e}_1 \mathbf{e}_2$.

Geometric Algebra (3)

If we use the **voltage-derived** choice of basis waveforms

$$\mathbf{e}_1 = \sqrt{2} \Re \left\{ \frac{V}{|V|} e^{j\omega t} \right\} \equiv \frac{v(t)}{|V|} \quad (3a)$$

$$\mathbf{e}_2 = \sqrt{2} \Im \left\{ \frac{V}{|V|} e^{j\omega t} \right\} \equiv \sqrt{2} \Re \left\{ -j \frac{V}{|V|} e^{j\omega t} \right\} \quad (3b)$$

where we recognize the Hilbert transform [\[Nowomiejski 1980\]](#), then

$v(t) \equiv \mathbf{v} = |V| \mathbf{e}_1$, and $\mathbf{i} = \frac{P}{|V|} \mathbf{e}_1 + \frac{Q_B}{|V|} \mathbf{e}_2$, so that

$$\mathbb{S} \equiv \mathbf{v} \mathbf{i} = P + Q_B \mathbf{e}_1 \mathbf{e}_2 \quad (4)$$

where $P = \Re\{VI^*\}$, and $Q_B = \alpha_1\beta_2 - \alpha_2\beta_1 = \Im\{VI^*\}$ Budeanu's reactive power [\[Budeanu 1927\]](#).

Geometric Algebra (4)

The *norm* of a multivector \mathbb{A} is defined as

$$\|\mathbb{A}\|^2 \triangleq \langle \mathbb{A}\mathbb{A}^\dagger \rangle_0 = \sum_{r=0}^N \|\langle \mathbb{A} \rangle_r\|^2$$

so

$$\|\mathbb{S}\|^2 = \|\mathbf{v}\|^2 \|\mathbf{i}\|^2 = P^2 + Q_B^2$$

The **grade structure** of a geometric algebra is symmetric, so that grade- r and grade- $(N - r)$ subspaces always have the same dimensions - correspondence via duality relation $\mathbb{A} \leftrightarrow \mathbb{A} \mathcal{J}$, pseudoscalar \mathcal{J} is the geometric product of a complete set of basis vectors, viz., $\mathcal{J} \triangleq \mathbf{e}_1 \mathbf{e}_2 \dots \mathbf{e}_N$.

$\mathbb{S} = P + Q_B \mathcal{J}$ shares key properties with the classical complex apparent power $S_c = P + jQ_B$.

Presentation Map

- Multivectors and Geometric Algebra,
- Polyphase Sinusoidal,
- Non-sinusoidal,
- Transients.

Three Phase Sinusoidal

The apparent power multivector $\mathbb{S} = \mathbf{v} \mathbf{i}$ now consists of 16 components: the scalar product $\langle \mathbf{v}, \mathbf{i} \rangle = P$ and 15 components of the wedge product $\mathbf{v} \wedge \mathbf{i}$; we redefine it to get a coarser (but physically meaningful) decomposition.

A voltage-derived basis - let $\eta_p = \left[\underbrace{0 \cdots 0}_p 1 0 \cdots 0 \right]$, so

$$\mathbf{e}_p \triangleq \sqrt{2} \Re \left\{ \frac{V_p}{|V_p|} e^{j\omega t} \right\} \eta_p \quad (5a)$$

and

$$\begin{aligned} \mathcal{H}(\mathbf{e}_p) &= \sqrt{2} \Re \left\{ -j \frac{V_p}{|V_p|} e^{j\omega t} \right\} \eta_p \\ &= \sqrt{2} \Im \left\{ \frac{V_p}{|V_p|} e^{j\omega t} \right\} \eta_p \end{aligned} \quad (5b)$$

Three Phase Sinusoidal (2)

The 3-phase waveform $v(t)$ and $i(t)$

$$v(t) = |V_1| \mathbf{e}_1 + |V_2| \mathbf{e}_2 + |V_3| \mathbf{e}_3$$

$$i(t) = i_v(t) + \mathcal{H}(i_w(t))$$

where

$$\mathbf{i}_v \equiv i_v(t) \triangleq \sum_{p=1}^3 \frac{\Re\{V_p I_p^*\}}{|V_p|} \mathbf{e}_p$$

$$\mathbf{i}_w \equiv i_w(t) \triangleq \sum_{p=1}^3 \frac{\Im\{V_p I_p^*\}}{|V_p|} \mathbf{e}_p$$

(6)

Three Phase Sinusoidal (3)

We redefine the apparent power multivector \mathcal{S} as a sum of two multivectors - first, the current multivector is

$$\mathbf{i} \triangleq \mathbf{i}_v + \mathbf{i}_w \mathcal{J} \quad (7)$$

and then

$$\mathcal{S} \triangleq \mathbf{v} \mathbf{i} = \mathcal{S}_v + \mathcal{S}_w \mathcal{J} \quad (8)$$

where

$$\mathcal{S}_v = \mathbf{v} \mathbf{i}_v = \underbrace{\langle \mathbf{v}, \mathbf{i}_v \rangle}_{\text{grade 0}} + \underbrace{\mathbf{v} \wedge \mathbf{i}_v}_{\text{grade 2}} \quad (9)$$

and

$$\mathcal{S}_w \mathcal{J} = \mathbf{v} \mathbf{i}_w \mathcal{J} = \underbrace{\langle \mathbf{v}, \mathbf{i}_w \rangle \mathcal{J}}_{\text{grade 3}} + \underbrace{(\mathbf{v} \wedge \mathbf{i}_w) \mathcal{J}}_{\text{grade 1}} \quad (10)$$

Three Phase Sinusoidal (4)

We will use the shorthand notations

$$P \triangleq \langle \mathbf{v}, \mathbf{i}_v \rangle, \mathbb{S}_g \triangleq \mathbf{v} \wedge \mathbf{i}_v \quad (11)$$

$$Q_B \triangleq \langle \mathbf{v}, \mathbf{i}_w \rangle, \mathbb{S}_b \triangleq \mathbf{v} \wedge \mathbf{i}_w$$

so that \mathbb{S}_g and \mathbb{S}_b are bi-vectors with 3 components each.

$$\mathbb{S} = \underbrace{P + \mathbb{S}_g}_{\mathbb{S}_v} + \underbrace{(Q_B + \mathbb{S}_b)}_{\mathbb{S}_w} \mathcal{J} \quad (12a)$$

$$\|\mathbb{S}\|^2 = \|\mathbf{v}\|^2 \|\mathbf{i}\|^2 = P^2 + \|\mathbb{S}_g\|^2 + Q_B^2 + \|\mathbb{S}_b\|^2 \quad (12b)$$

using all four grades (0,1,2,3) of the geometric algebra generated by the three-dimensional vector space spanned by $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$. In fact, $\mathbb{S}_v = P + \mathbb{S}_g$ is a **quaternion**, and so is $\mathbb{S}_w = Q_B + \mathbb{S}_b$.

Polyphase Sinusoidal

This extension follows directly

$$\mathbb{S} = \underbrace{P}_{\text{grade } 0} + \underbrace{\mathbb{S}_g}_{\text{grade } 2} + \underbrace{Q_B \mathcal{J}}_{\text{grade } n} + \underbrace{\mathbb{S}_b \mathcal{J}}_{\text{grade } n - 2}$$

The statistical interpretation of the four components of \mathbb{S} in terms of the distributions of equivalent conductances $\{g_p\}$ and susceptances $\{b_p\}$ is unchanged from our previous, projection-based work.

Presentation Map

- Multivectors and Geometric Algebra,
- Polyphase Sinusoidal,
- Non-sinusoidal,
- Transients.

Non-Sinusoidal

Previous results largely unchanged if we can derive a voltage-based orthonormal basis - decide on which harmonics are important

$$\Omega_v \triangleq \{k; |V_k| > \varepsilon\}$$

we define a set of orthonormal basis waveforms

$$\mathbf{e}_k \triangleq \sqrt{2} \Re \left\{ \frac{V_k}{|V_k|} e^{jk\omega t} \right\}, \quad k \in \Omega_v \quad (13)$$

and use the Euclidean space $\text{span}\{\mathbf{e}_k; k \in \Omega_v\}$ to generate the corresponding geometric algebra.

$$\begin{aligned} i(t) &= \sum_{k \in \Omega_v} \sqrt{2} \Re\{I_k e^{jk\omega t}\} + \underbrace{\sum_{k \notin \Omega_v} \sqrt{2} \Re\{I_k e^{jk\omega t}\}}_{i_{\perp}(t)} \\ &= i_v(t) + \mathcal{H}(i_w(t)) + i_{\perp}(t) \end{aligned} \quad (14)$$

Non-Sinusoidal (2)

We have a 5-component decomposition of the apparent power, consisting of the out-of-band (unsigned) component $\|\mathbf{v}\| \|\mathbf{i}_\perp\| \triangleq S_\perp$ and a four-component multivector

$$\mathbb{S} = P + \mathbb{S}_g + (Q_B + \mathbb{S}_b) \mathcal{J} \quad (15a)$$

such that

$$\|\mathbf{v}\|^2 \|\mathbf{i}\|^2 = \underbrace{P^2 + \|\mathbb{S}_g\|^2 + Q_B^2 + \|\mathbb{S}_b\|^2}_{\|\mathbb{S}\|^2} + S_\perp^2 \quad (15b)$$

The polyphase version is the same, except that the set of voltage-derived basis vectors is doubly indexed (phase and harmonic)

Decussis Mirabilis: 1927-1937



Constantin Budeanu (1886-1959)

$$S^2 = P^2 + Q_B^2 + D^2$$



Stanislaw Fryze (1885-1964)

$$i_a(t) = \frac{\langle i^\top v \rangle}{\langle v^\top v \rangle} v(t)$$



Wilhelm Quade (1898-1975)

Funktionenraums

Reactive Power - Schools

- **Romania:** A.D. Iliovici (1925), C. Busila, C. Budeanu, I. Antoniu (1950), F. Manea, V. Nedelcu (1960) M. Milic (1970), A. Tugulea, A. Emanuel,
- **Poland:** S. Fryze, M. Erlicki (1950), Z. Nowomiejski (1980), L. Czarnecki,
- **Germany:** F. Buchholz (1920), W. Quade (1930), R. Richter (1930), M. Depenbrock (1970), H. Fisher (1980).

Presentation Map

- Multivectors and Geometric Algebra,
- Polyphase Sinusoidal,
- Non-sinusoidal,
- Transients.

Instantaneous Reactive Power

The instantaneous apparent power is

$$s(t) = \sqrt{[v(t) \ v^\top(t)][i(t) \ i^\top(t)]}$$

$$s^2(t) - p^2(t) = \sum_{r < m} q_{rm}^2(t) \quad (16)$$

where $q_{rm}(t)$ are the (strictly above diagonal) elements of the skew-symmetric matrix

$$Q(t) \triangleq i^\top(t)v(t) - v^\top(t)i(t) \quad (17)$$

usually referred to as the “instantaneous reactive power”.

Instantaneous Reactive Power (2)

In a three-phase $a - b - c$ system there are three instantaneous reactive power quantities, viz., $q_{ab}(t)$, $q_{ac}(t)$ and $q_{bc}(t)$.

Some authors proposed interpreting $q_{rm}(t)$ as the three components of a vector (cross) product between the current vector $i(t)$ and the voltage vector $v(t)$. However, this interpretation does not carry over to $n > 3$.

The entries of $Q(t)$ depend on coordinates chosen (e.g., $a - b - c$ vs. symmetrical components vs. Park transformed).

The **instantaneous apparent power multivector** is again a quaternion

$$\mathcal{S} \triangleq i v = i \cdot v + i \wedge v \quad (18)$$

Instantaneous Reactive Power (3)

Instantaneous **Akagi-Nabae** compensation achieves $p(t) = s(t)$ by forcing the compensated load current to equal

$$i_a(t) = \frac{i(t) v^\top(t)}{v(t) v^\top(t)} v(t)$$

In the periodic case we can establish (unfortunately quite tenuous) links with average power quantities:

$$P = \frac{1}{T} \int_T p(t) dt = \langle p(t) \rangle_0$$

$$S = \sqrt{\langle i(t) i^\top(t) \rangle_0 \langle v(t) v^\top(t) \rangle_0}$$

so that, in general, $S^2 \neq \langle s(t) \rangle_0^2 \neq \langle s^2(t) \rangle_0$, as well as $P^2 \neq \langle p^2(t) \rangle_0$. All one can say with certainty is $\langle s(t) \rangle_0 \leq S$.

Doing it Right - Dynamic Phasors

$x(t - \Delta)$ on the interval $[0 \leq \Delta < T_0)$ via (short-time) Fourier series:

$$x(t - \Delta) = \sum_{k=-\infty}^{\infty} X_k(t) e^{jk\omega_0(t-\Delta)} = \sum_{k=-\infty}^{\infty} e^{-jk\omega_0\Delta} \mathcal{X}_k(t)$$

$X_k(t)$ are the complex, time-varying Fourier coefficients, or **dynamic phasors**.

Doing it Right - Dynamic Phasors

$x(t - \Delta)$ on the interval $[0 \leq \Delta < T_0)$ via (short-time) Fourier series:

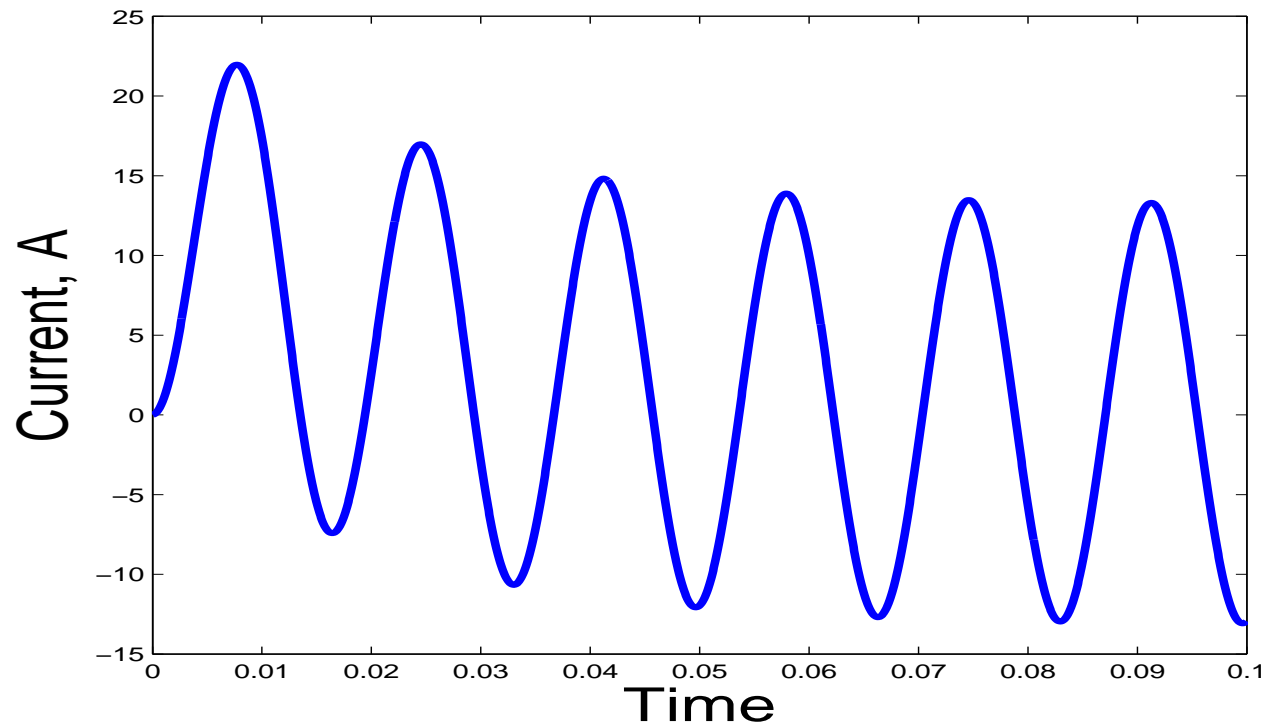
$$x(t - \Delta) = \sum_{k=-\infty}^{\infty} X_k(t) e^{jk\omega_0(t-\Delta)} = \sum_{k=-\infty}^{\infty} e^{-jk\omega_0\Delta} \mathcal{X}_k(t)$$

$X_k(t)$ are the complex, time-varying Fourier coefficients, or **dynamic phasors**.

$$X_k(t) = \frac{1}{T_0} \int_{t-T_0}^t x(\tau) e^{-jk\omega_0\tau} d\tau = \langle x \rangle_k(t)$$

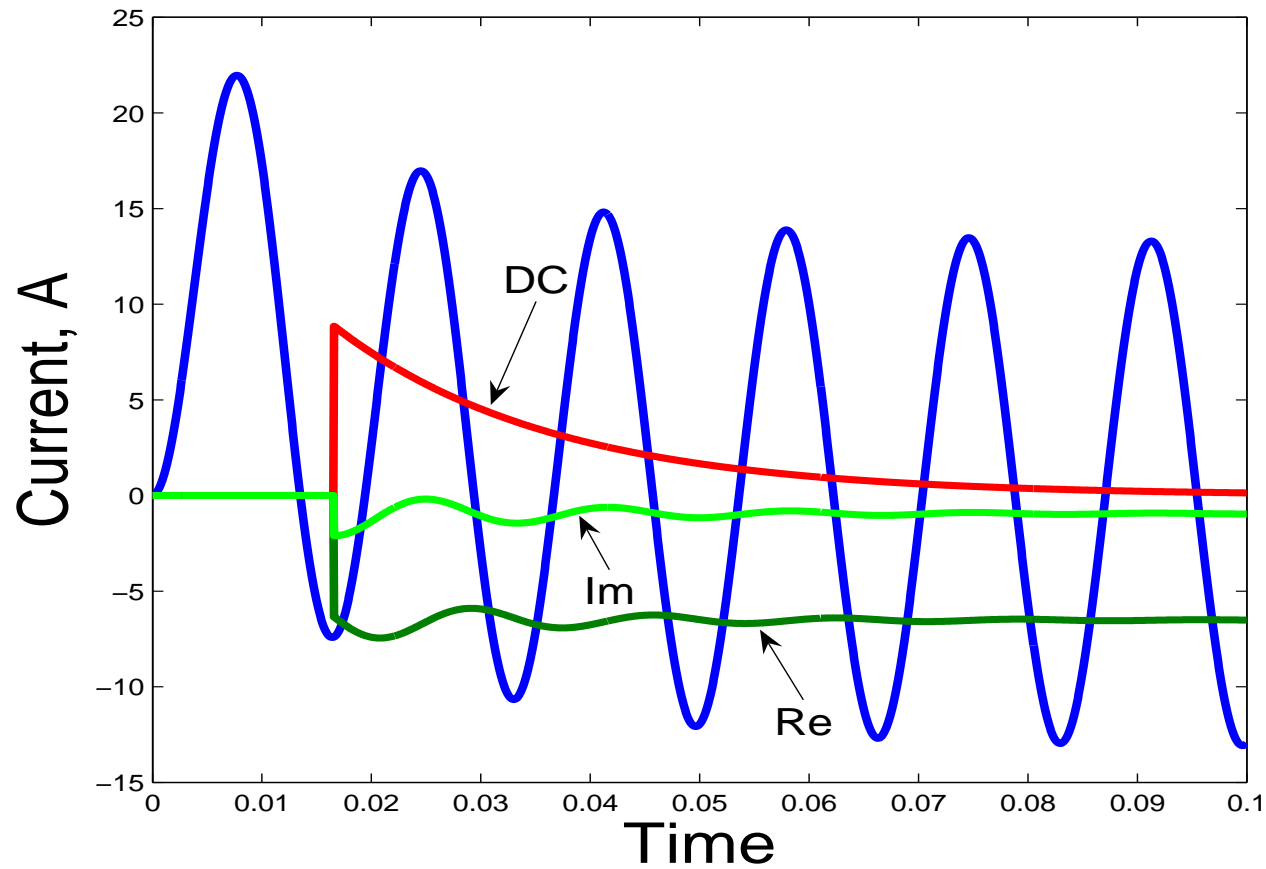
A Simple Example

Consider a simple RL circuit ($R=0.1$, $L=0.002$) with a \sin excitation ($V=10$), at 60Hz



A Simple Example (2)

The dynamic phasors (according to our definition)



Extensions - Classical

Dynamic symmetrical components - recall $\alpha = e^{j\frac{2\pi}{3}}$,

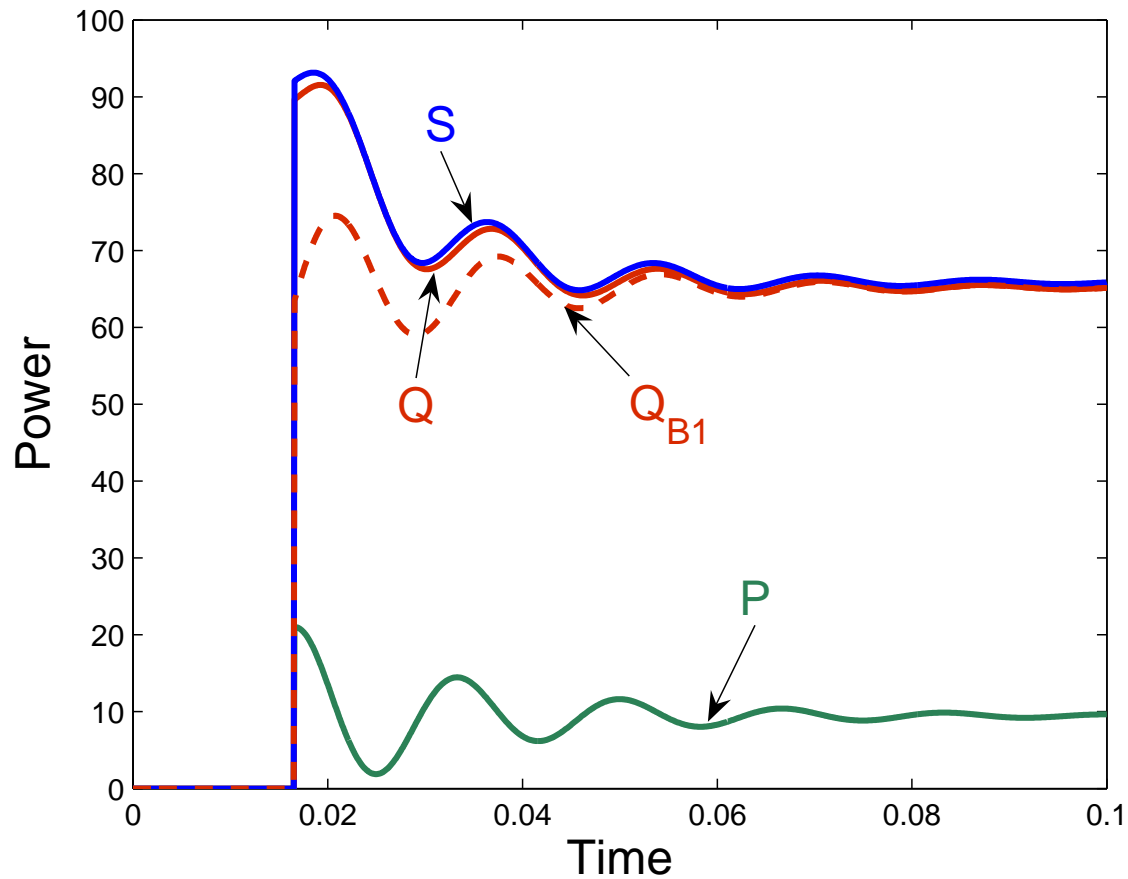
$$\begin{bmatrix} x_a \\ x_b \\ x_c \end{bmatrix} (\tau) = \sum_{k=-\infty}^{\infty} e^{jk\omega_0\tau} \underbrace{\frac{1}{\sqrt{3}} \begin{bmatrix} 1 & 1 & 1 \\ \alpha^* & \alpha & 1 \\ \alpha & \alpha^* & 1 \end{bmatrix}}_F \begin{bmatrix} X_{p,k} \\ X_{n,k} \\ X_{z,k} \end{bmatrix} (t)$$

$$\begin{bmatrix} X_{p,k} \\ X_{n,k} \\ X_{z,k} \end{bmatrix} (t) = \frac{1}{T_0} \int_{t-T_0}^t e^{-jk\omega_0\tau} F^H \begin{bmatrix} x_a \\ x_b \\ x_c \end{bmatrix} (\tau) d\tau = \begin{bmatrix} \langle x \rangle_{p,k} \\ \langle x \rangle_{n,k} \\ \langle x \rangle_{z,k} \end{bmatrix} (t).$$

$$\frac{d}{dt} \begin{bmatrix} X_{p,k} \\ X_{n,k} \\ X_{z,k} \end{bmatrix} (t) = F^H \begin{bmatrix} \langle \frac{d}{d\tau} x_a(\tau) \rangle_k \\ \langle \frac{d}{d\tau} x_b(\tau) \rangle_k \\ \langle \frac{d}{d\tau} x_c(\tau) \rangle_k \end{bmatrix} (t) - jk\omega_0 \begin{bmatrix} X_{p,k} \\ X_{n,k} \\ X_{z,k} \end{bmatrix} (t)$$

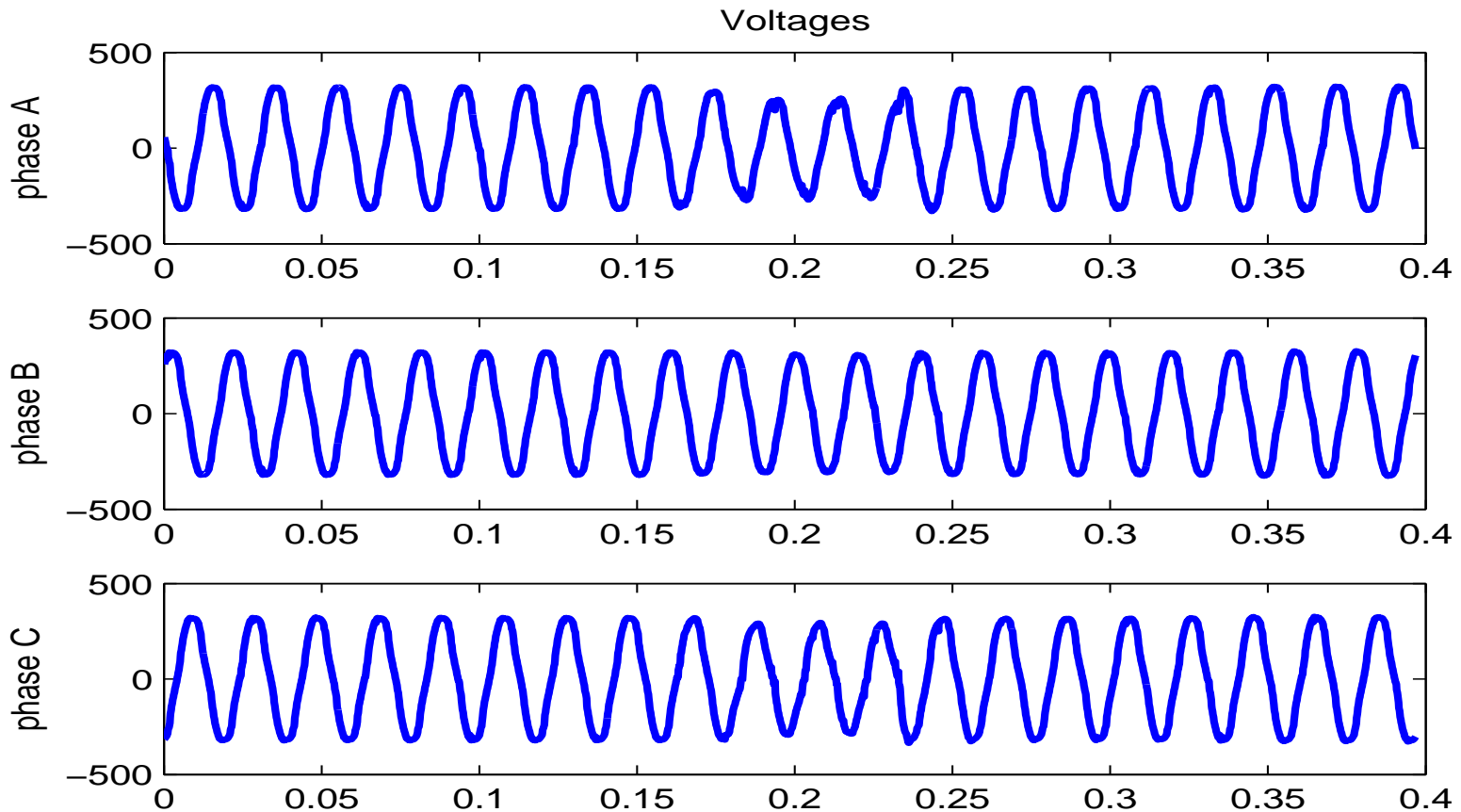
Reactive Power in the Example

Our inductor example

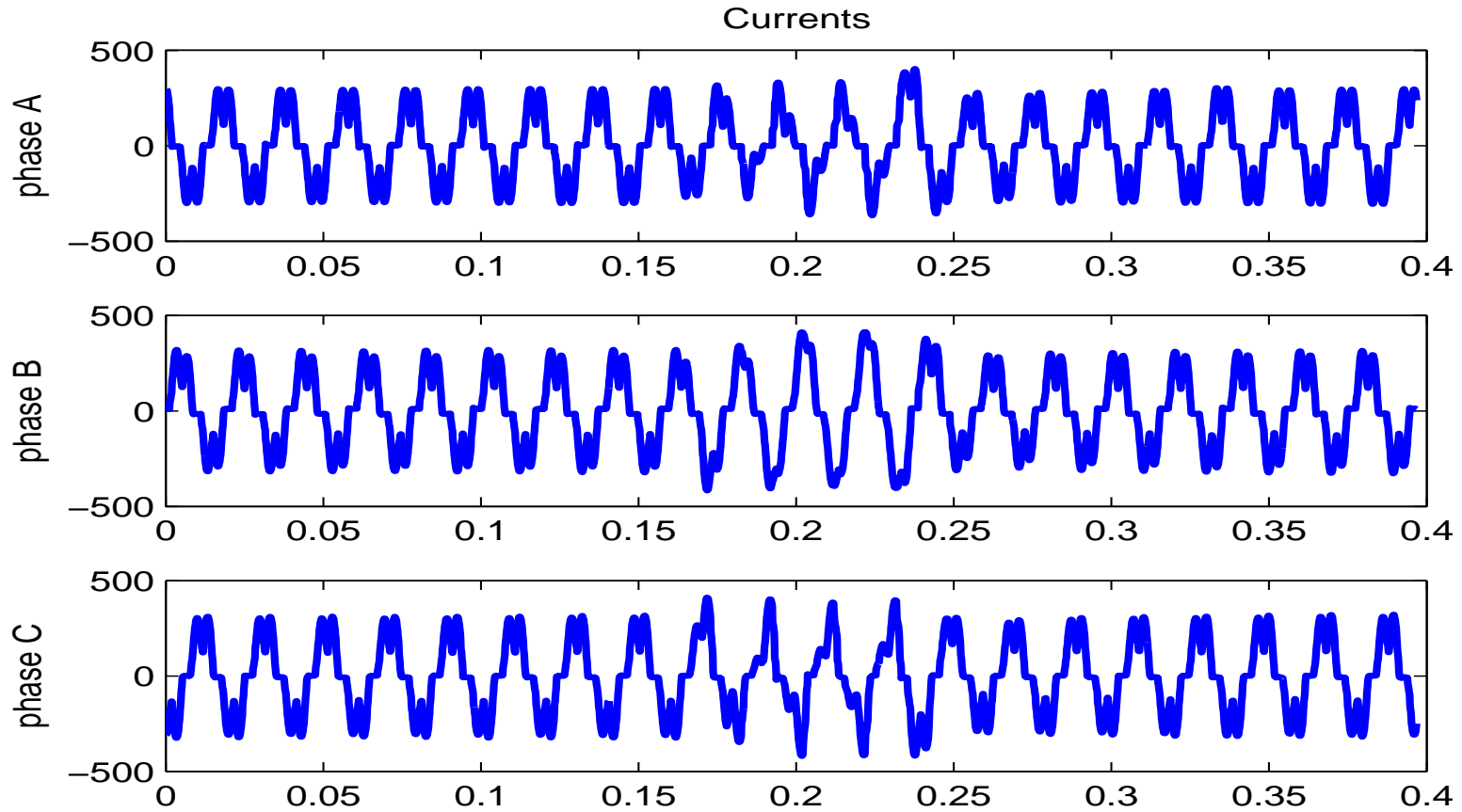


An Industrial Example

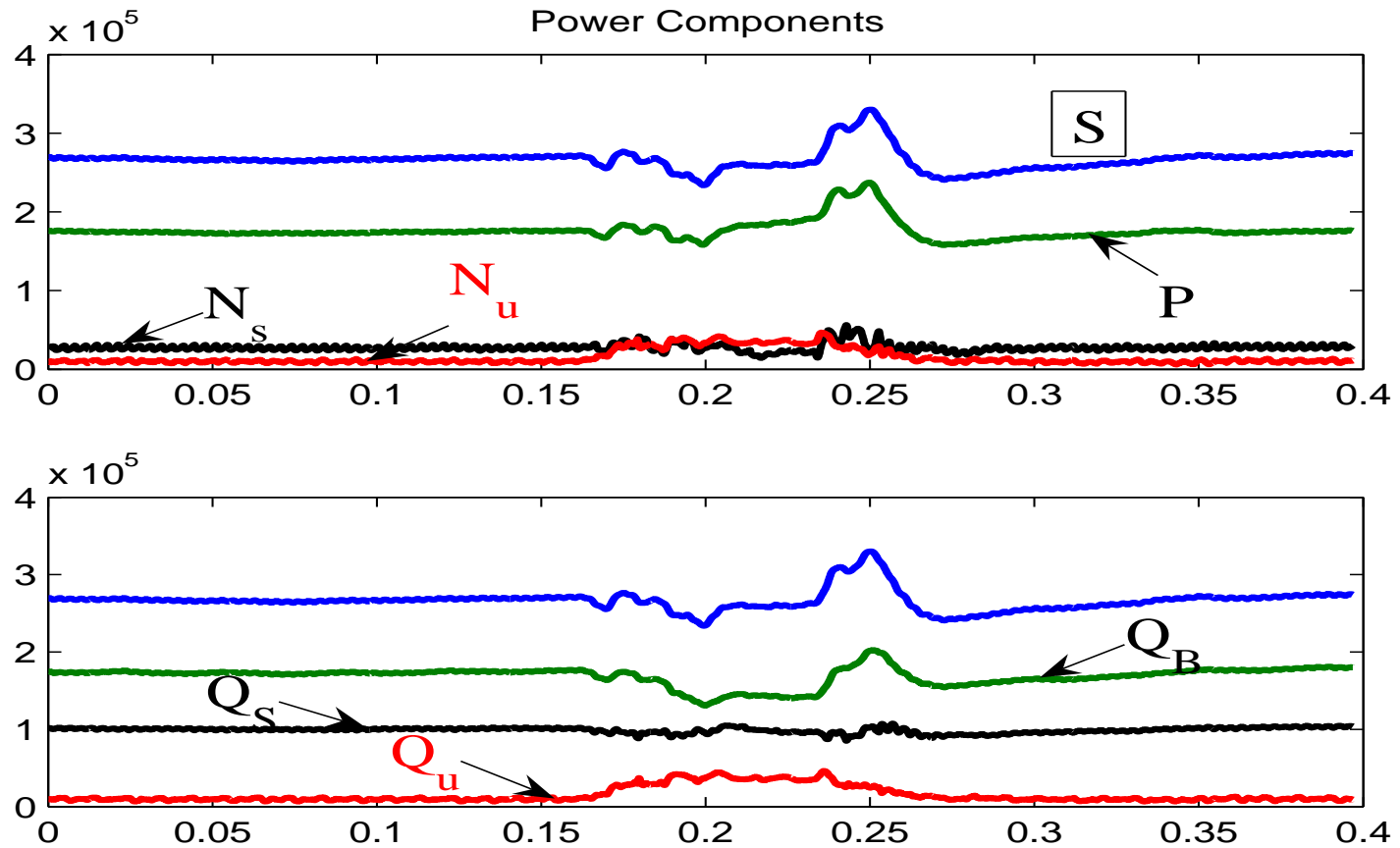
Paper plant transient



Industrial Example (2)



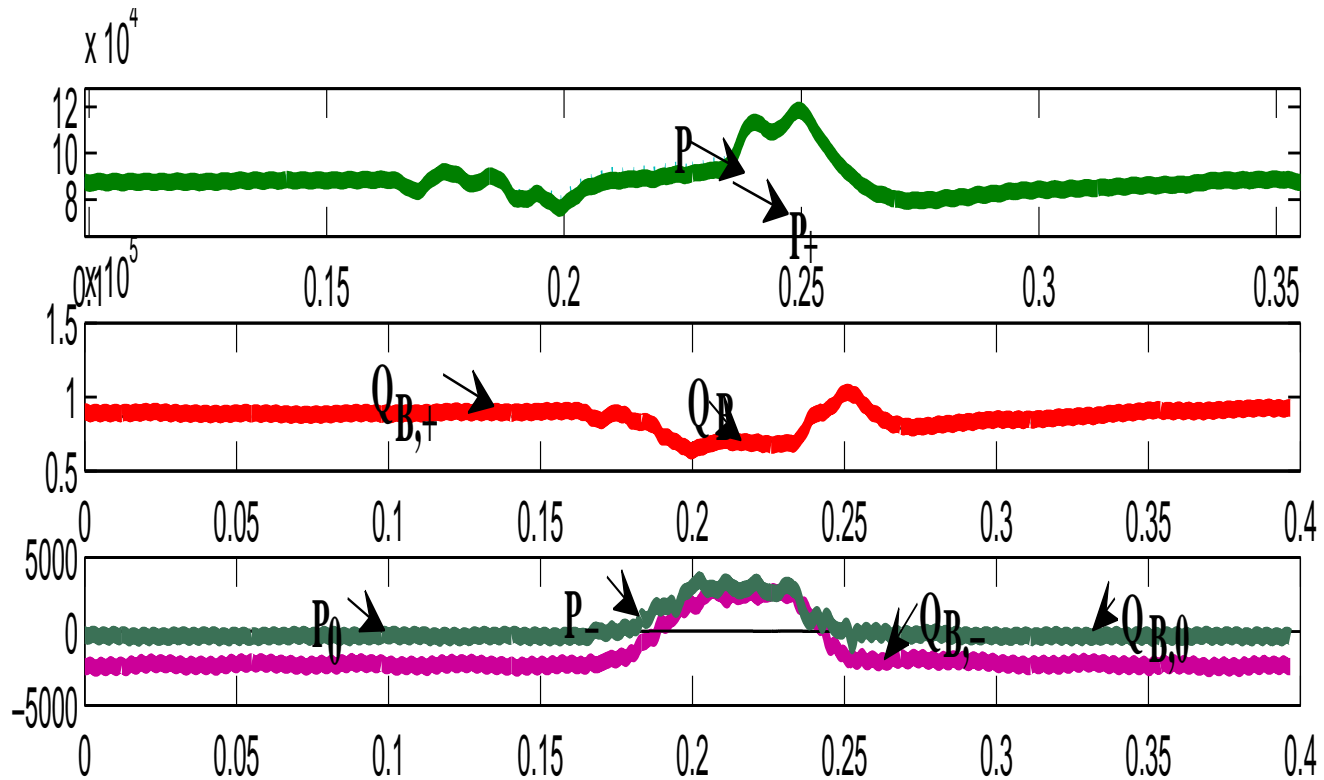
Industrial Example via Phasors (3)



Industrial Example via Phasors (4)

Decomposing signed components - two level decomposition:

$$P = P_+ + P_- + P_0 \quad Q_B = Q_{B+} + Q_{B-} + Q_{B0}$$



Conclusions

- The reactive power story is an old (and formidable) problem,

Conclusions

- The reactive power story is an old (and formidable) problem,
- It has evolved as performance goals and compensation means have changed,

Conclusions

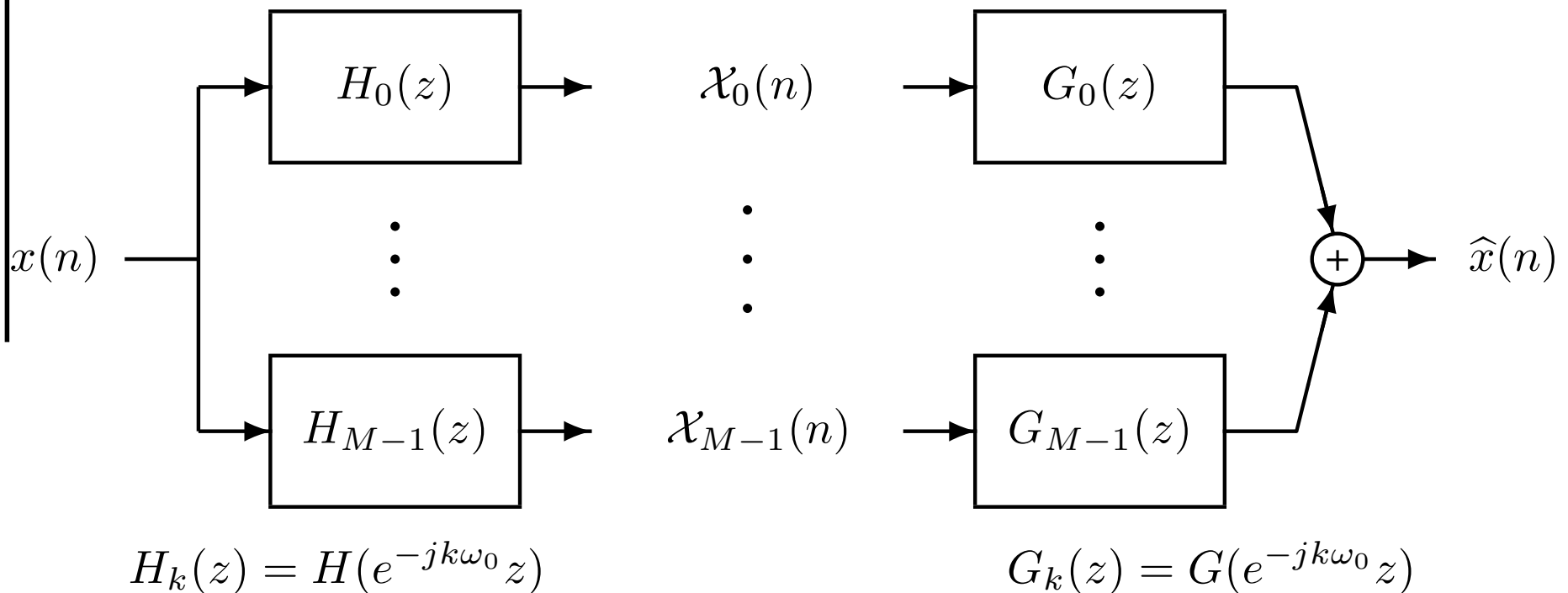
- The reactive power story is an old (and formidable) problem,
- It has evolved as performance goals and compensation means have changed,
- Reading papers by old masters is a rewarding (and ego-shrinking) experience,

Conclusions

- The reactive power story is an old (and formidable) problem,
- It has evolved as performance goals and compensation means have changed,
- Reading papers by old masters is a rewarding (and ego-shrinking) experience,
- The electric energy engineering - *Ars Longa, Vita Brevis*.

Extensions - Phasor Banks

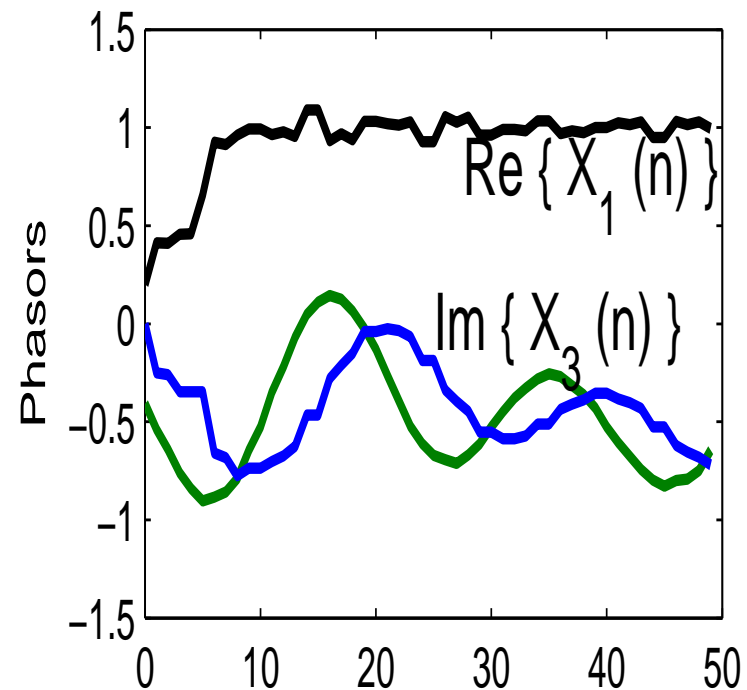
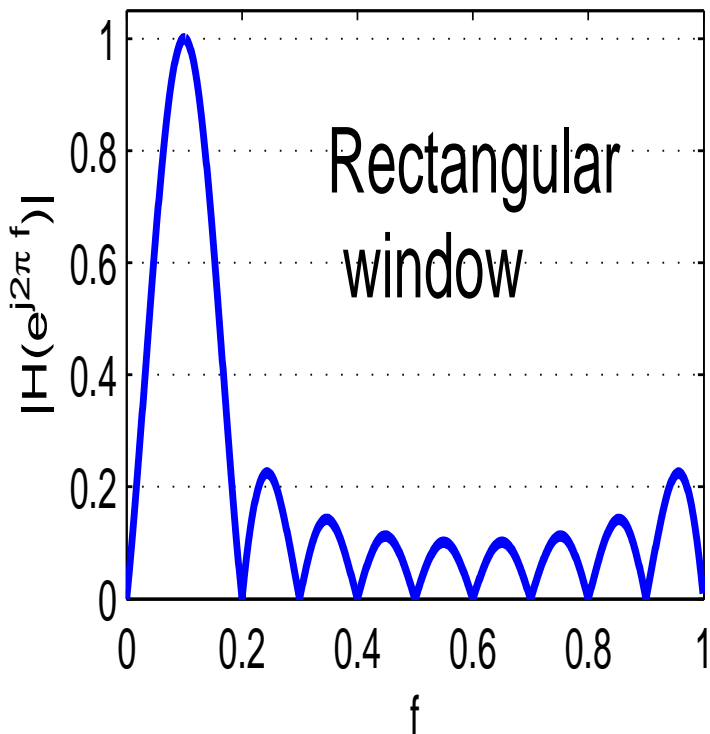
With H. Lev-Ari – in discrete-time, standard definitions lead to (discrete-time) Gabor Transform – **non-decimated** DFT analysis and synthesis banks:



Phasor Banks (2)

An example - a fundamental and a slowly modulated third harmonic:

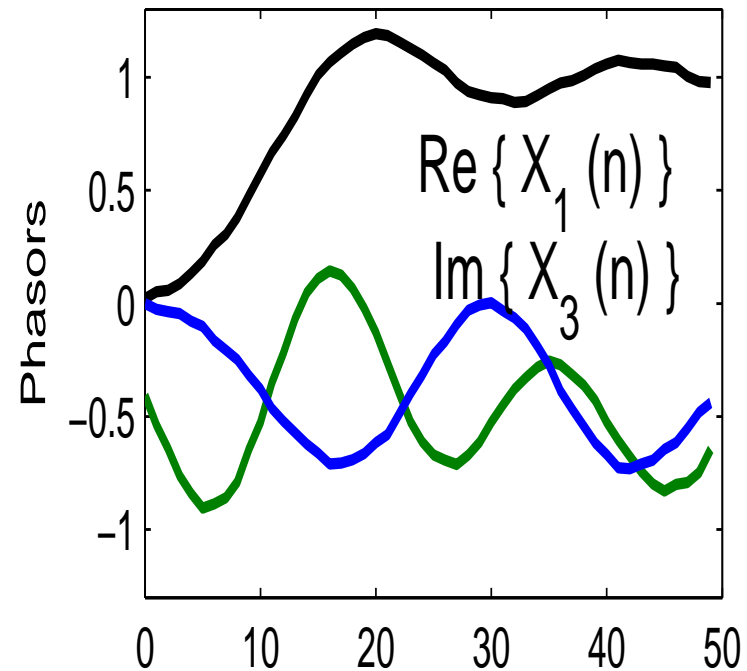
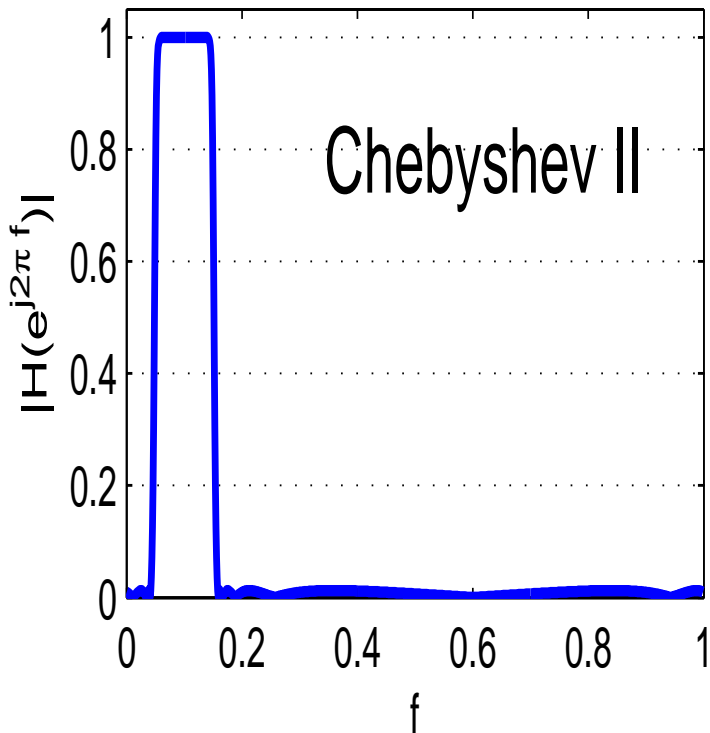
$$x(n) = 2 \cos(\omega_0 n) + a(n) \sin(3\omega_0 n)$$



Phasor Banks (3)

The same example:

$$x(n) = 2 \cos(\omega_0 n) + a(n) \sin(3\omega_0 n)$$



Other Applications

Power electronics:

- DC/DC converters (model reduction),
- Resonant converters,
- Active filters,
- High-power converters - Unified Power Factor Controller.

Electric Drives:

- Unbalanced electrical machines,
- Torque ripple minimization,
- Position-dependent loads.

Power Systems:

- Unbalanced faults - dynamic symmetrical components,
- Model-based estimation,
- Protection.