

G 364: Mobile and Wireless Networking

CLASS 8, Mon. Feb. 2 2004

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M-W, 11:40am-1:20pm, 109 Rob

Technical Challenges for the Ad Hoc Architecture

- ◆ Given **node mobility**: Every node in the network can move unpredictably and independently, at variable speed
- ◆ Given **a very large number of nodes**: For supporting pervasive computing, sensing of large geographic areas, etc.
- ◆ Given the nodes' **limited resources**
- Network protocols need to be **robust, reliable** and **scalable** (which makes the network such)

Multipoint Communications, 1

The most general form of communication.
It includes:

- ◆ One-to-one (routing)
- ◆ One-to-many (multicast)
- ◆ One-to-all (broadcast)
- ◆ Many-to-many (gossiping)

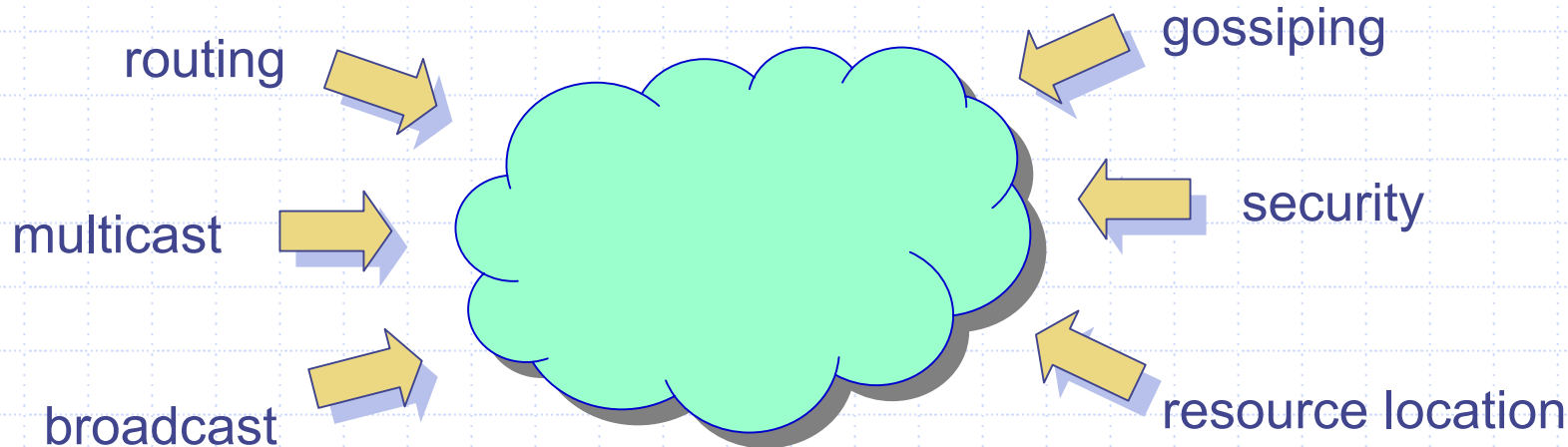
Multipoint Communications, 2

Previous approaches:

- ◆ Focus on a single communication problems
- ◆ Several diverse techniques (not efficiently “reusable”)
- ◆ Have to maintain communication information at each node (state information)
- ◆ Devote lots of resources to control traffic

A Unifying Approach

- ◆ An architectural concept that implements network services and communication protocols without maintaining communication information at the nodes



Inside the Cloud

◆ A:

- Fast and simple
- Resource efficient
- Mobility adaptive
- Node-status dependent

node selection mechanism to efficiently select and maintain ONLY a small subset of nodes for implementing network services and protocols

How to Select the Best Nodes

- ◆ Independence of the clusterheads
- ◆ Dominance of the clusterheads
- ◆ Possibility to express “preferences”
- ◆ Distributed operations
- ◆ Fast and simple implementation

Previous Approaches

- ◆ Heuristics based on Independent Sets
 - Minimum ID approach (Gerla & al.)
 - Maximum degree (Ephremides & al.)
- ◆ Heuristics based on Dominating Sets
 - The concept of “spine”
 - Minimum connected dominating set

Previous Approaches: Drawbacks

- ◆ No preferences
- ◆ Clustering “set up” differs from clustering maintenance
- ◆ One *and* two hops neighbors have to be known at each node
- ◆ Problems with nodes mobility
- ◆ No analytical results

MWIS-Based Clustering

- ◆ MWIS = Maximal Weight Independent Set
- ◆ Clustering selection based on generic **weights** (real numbers > 0)
 - Mobility/node related parameters
 - Generalizes previous “Independent Set” solutions

Two Protocols

- ◆ Distributed Clustering Algorithm (DCA)
 - Quasi-mobile networks, periodical reclustering. Allow complexity analysis, fast and simple
- ◆ Distributed and Mobility-Adaptive Clustering (DMAC) Algorithm
 - Same rules/procedures for clustering set up and maintenance, adaptive to nodes mobility and node/link failures

DCA: Distributed Clustering Algorithm, 1

◆ Assumptions

- Knowledge of IDs and weights of one-hop neighbors
- Broadcast transmission of a packet in finite time (a “step”)
- Nodes do not move during clustering

DCA, 2

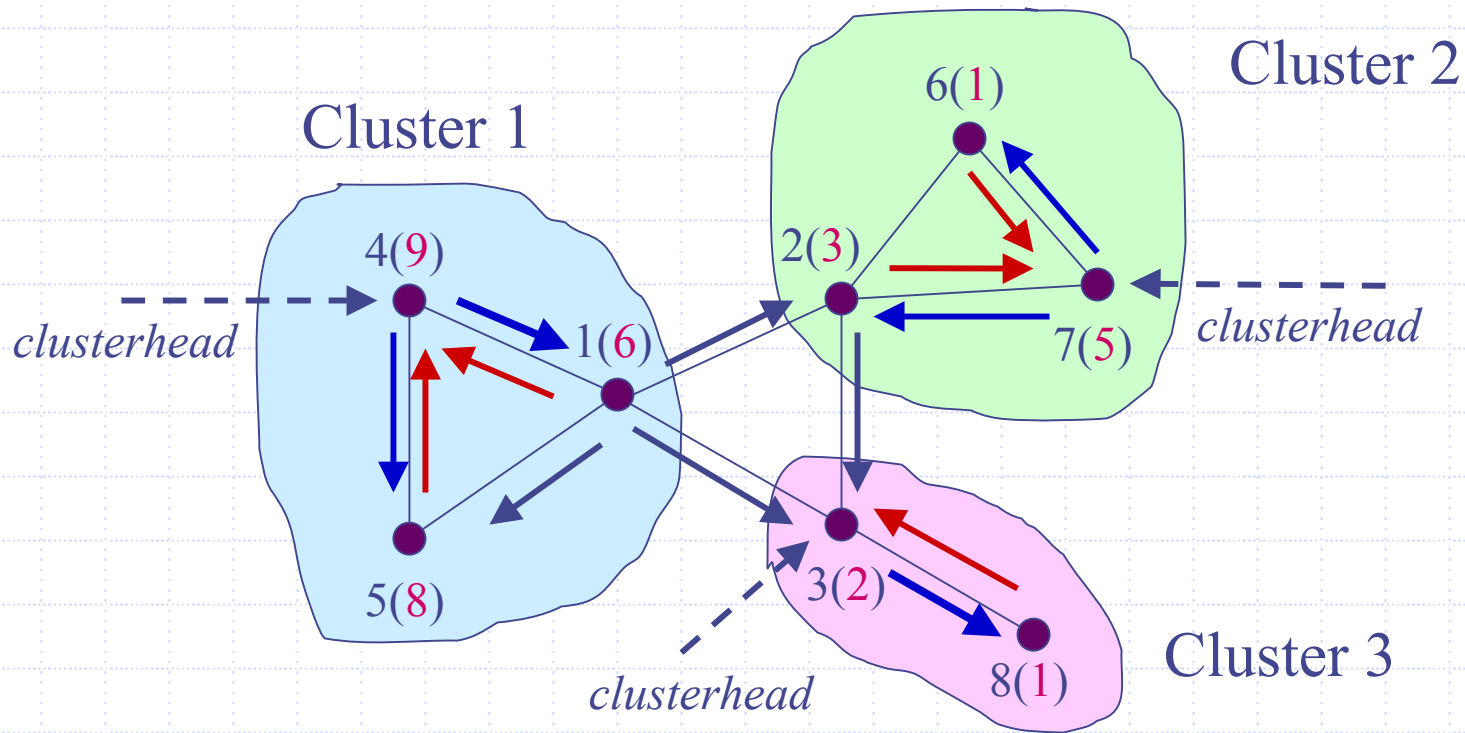
◆ (Only) Two messages:

- CH(v): Sent by a clusterhead v
- JOIN(u,t): Sent by ordinary node u when it joins the cluster of clusterhead t

◆ Three (simple) procedures:

- Init (start up)
- OnReceivingCH(v), OnReceivingJOIN(u,v)
(message triggered)

Example



I Step
2/2/04

II Step

III Step

IV Step

V Step 14

DCA: Provable Properties

◆ Consider

$$\tau: V \rightarrow \{1, 2, 3, \dots, 2k\}$$

V = set of network nodes, k = number of clusters

◆ **Proposition:** Each node v in V sends exactly one message by $\tau(v)$ steps

◆ **Corollary 1:** DCA message complexity is $n = |V|$

◆ **Corollary 2:** DCA terminates correctly in at most $2k$ steps ($\leq 2n$)

A Note on the Average Time Complexity

◆ We notice that

$$k \leq \alpha(G)$$

G = topology graph, $\alpha(G)$ = G 's *stability number*

◆ We see the network as a *random graph*, for which

$$(2k \leq) \alpha(G) = \text{circa } O(\log n)$$

Log's base is a function of n and the number of the network links

Assignments

- ◆ Read the paper for HMW # 2
- ◆ Updated information on the class web page:

www.ece.neu.edu/courses/eceg364/2004sp